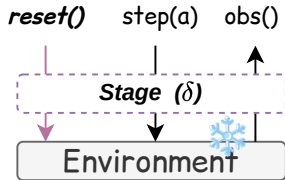
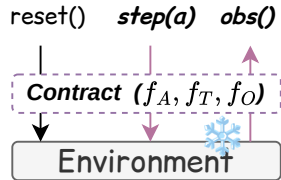


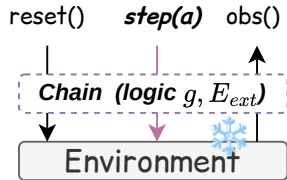
```
def reset():
    state = s0
def step(a):
    state = T(state, a)
def obs():
    return 0(state)
```



```
def reset():
    state = s0
    for a in delta:
        state = T(state, a)
```



```
def step(a):
    a = f_A(a)
    state = f_T(a, state)
def obs():
    return f_O(state)
```



```
def step(a):
    state = T(state, a)
    if g(state):
        state = env_B.s0
```